

**Development of a Velocity  
Reconstruction Algorithm for AMS  
RICH**  
results from Prototype data

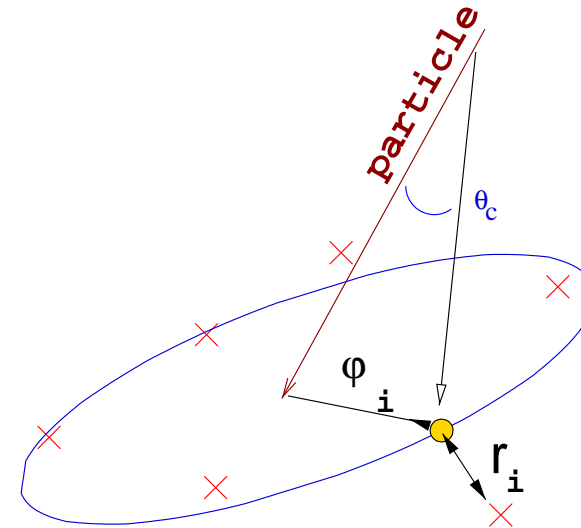
F. Barão , **J.Borges**

## Summary

- ❑ The reconstruction method
  
- ❑ Results from RICH Flight setup (MC)
  
- ❑ Results from RICH prototype (Data .vs. MC)
  
- ❑ Future prospections and Conclusions

## $(\theta_c)$ reconstruction: A pattern fit procedure

- ✓ The AMS Tracker provides the **particle direction**  $(\theta, \phi)$  and **impact point** at the RICH radiator
- ✓ The **photon pattern** at the PMT matrix plane is computed, leaving  $\theta_c$  as the only free parameter for fit
- ✓ The hits associated to the particle track are excluded
- ✓ The **maximization of a likelihood function** provides the **best  $\theta_c$  angle**



Range for  $\theta_c$  search :  
 $(2^\circ, 1.1 \times \text{acos}(\frac{1}{n}))$   
 where n is the nominal radiator refractive index

$$P(\theta_c) = \prod_{i=1}^{nhits} P_i\{r_i(\varphi_i(\theta_c); \theta_c)\}$$

$r_i \equiv$  closest distance to photon pattern

$P_i \equiv$  probability of a hit belonging to photon pattern

# $\theta_c$ reconstruction: probability function summary

- ✓ noisy hits distribution essentially flat  
**PMT noise, scattering,...**

$$P_{noise} = \frac{b}{R} \sim 10^{-3} \text{ cm}^{-1}$$

$b \equiv$  photon background fraction

$R \equiv$  PMT matrix dimension

- ✓ pattern hits distribution essentially gaussian  
**pixel size, radiator thickness, chromaticity,...**

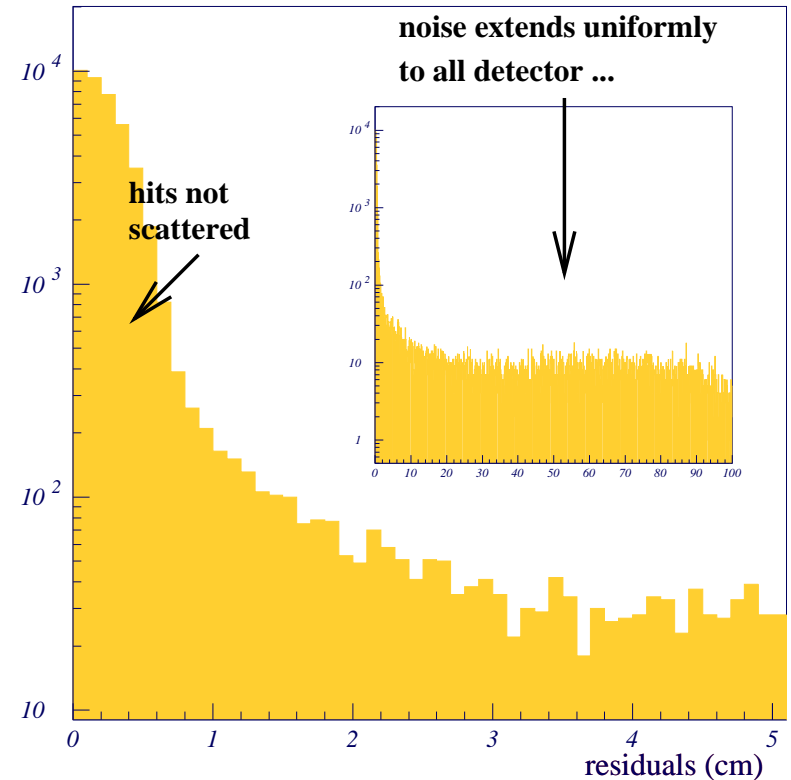
$$P_{signal}(r) = (1 - b) \frac{1}{\sigma \sqrt{2\pi}} \exp^{-\frac{1}{2} \left(\frac{r}{\sigma}\right)^2}$$

$$\sigma \sim 0.5 \text{ cm}$$

- ✓ combined probability function

$$P_i(r_i) = (1 - b) P_{signal}(r_i) + \frac{b}{R}$$

- ✓ Advantage of likelihood : **being insensitive to noise spread all over the RICH matrix**



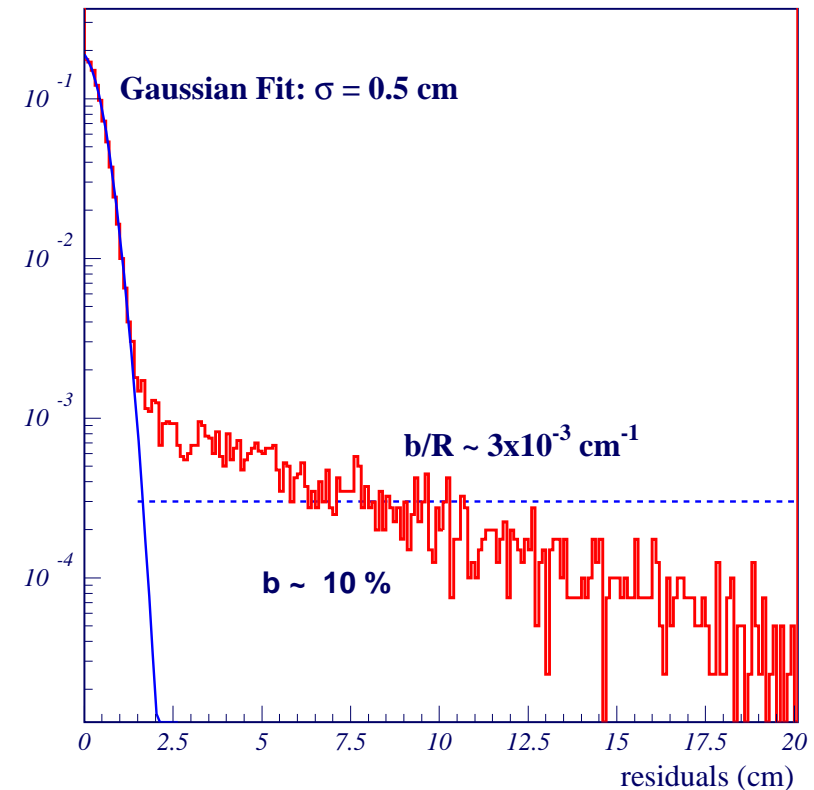
for FLIGHT SETUP (simulation)

## $\theta_c$ reconstruction: probability function optimization

for PROTOTYPE (simulation)

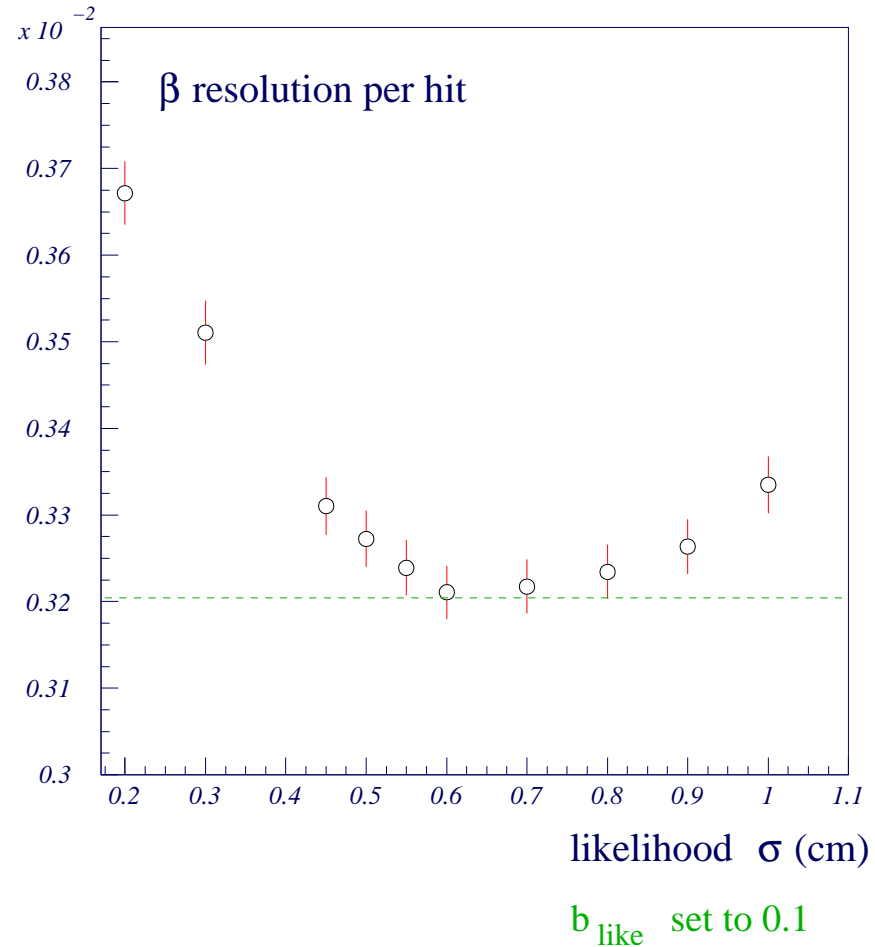
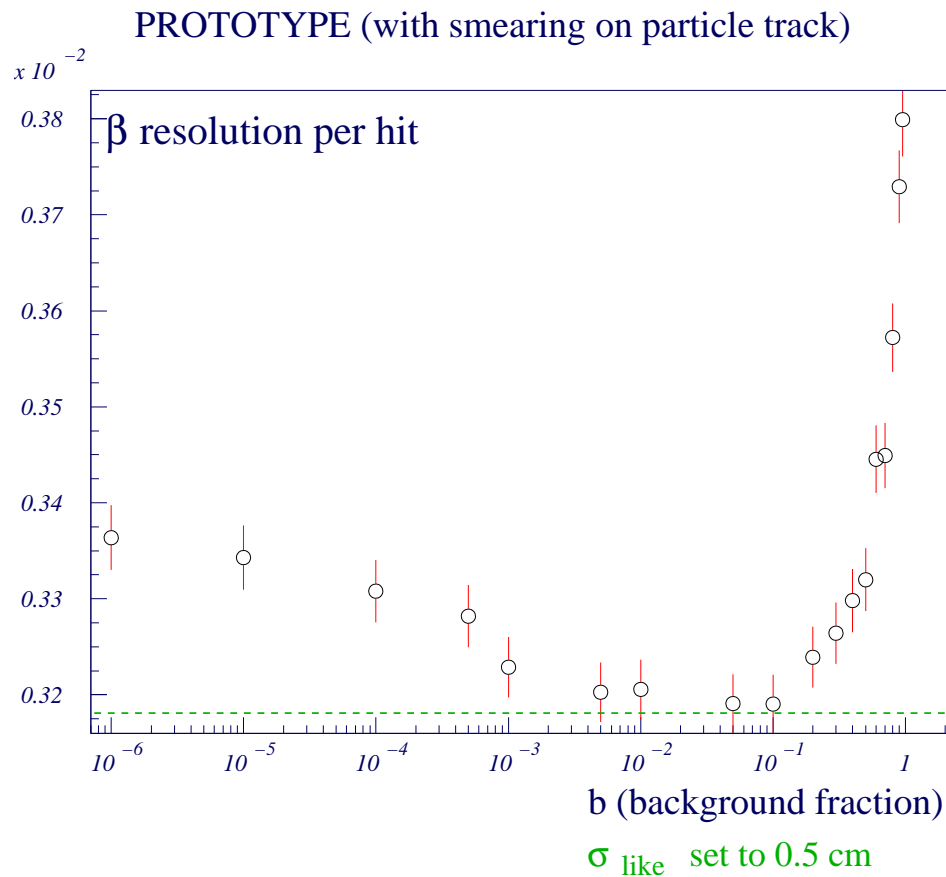
1 - Evaluate parameters  $\sigma$  and  $b$  from the residuals obtained by a standard reconstruction (residuals from simulation points out the values)

- $\sigma$  parameter :  
fit Gaussian slice of residuals (with information about  $\theta_C$ )
- $b$  parameter :  
Geometrical effects modulate background residuals distribution .  
Assume flat distribution .



# $\theta_c$ reconstruction: probability function optimization

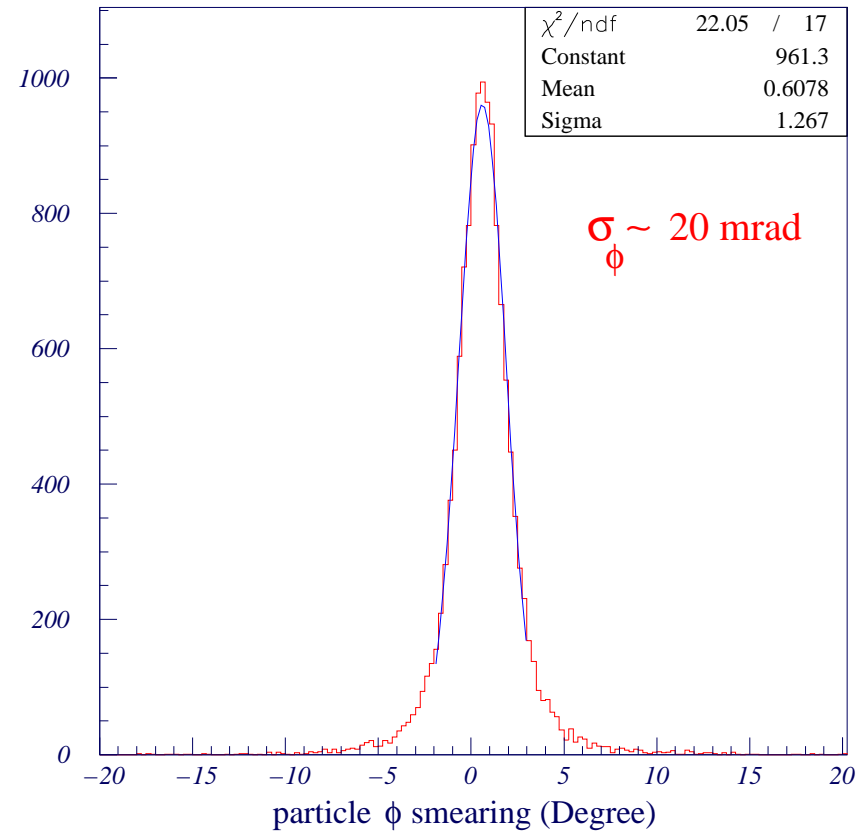
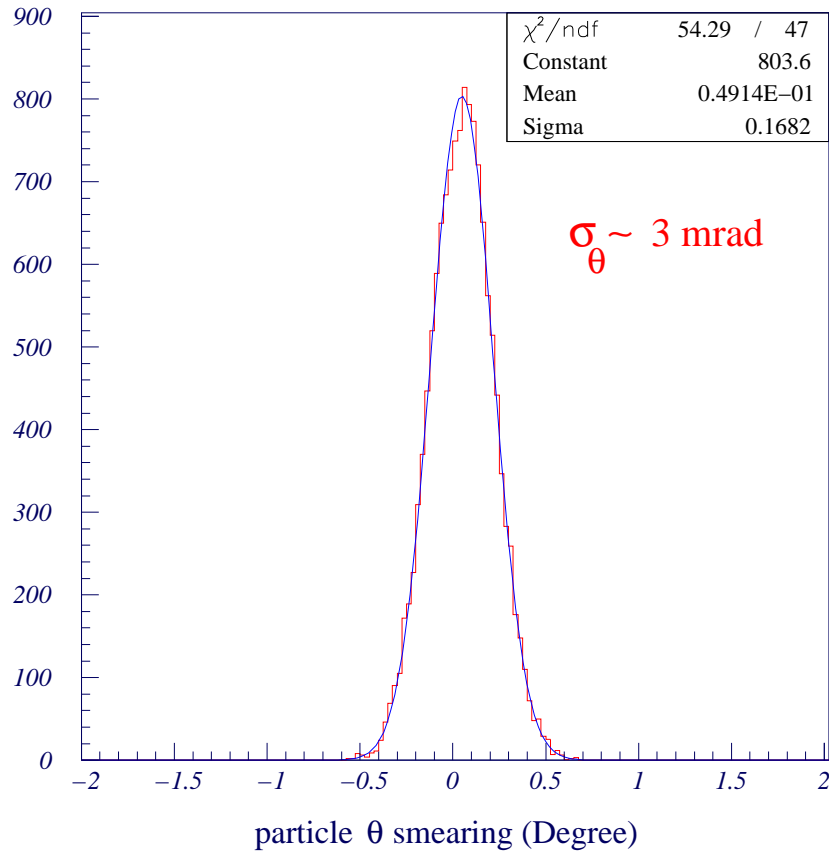
## 2 - Test robustness of likelihood to choice of parameters



good agreement with values estimated from residuals !

# $\theta_c$ reconstruction: effect of track resolution on $\beta$ resolution

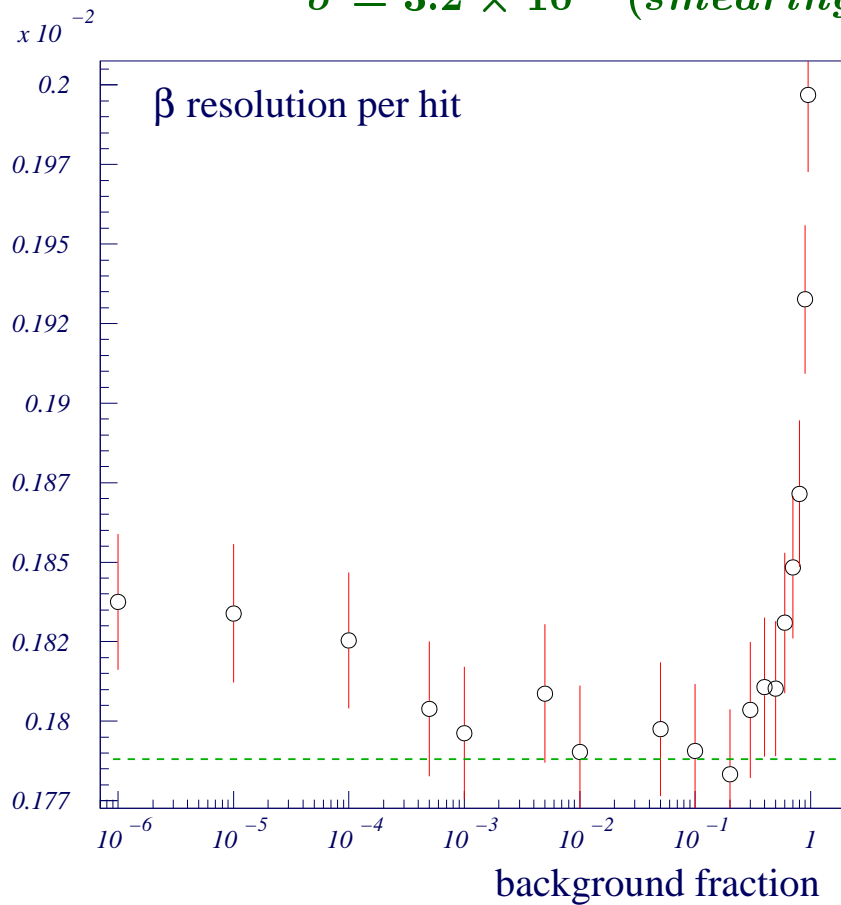
Track resolution for particle direction ( $\theta, \phi$ ) due to smearing (simulation)



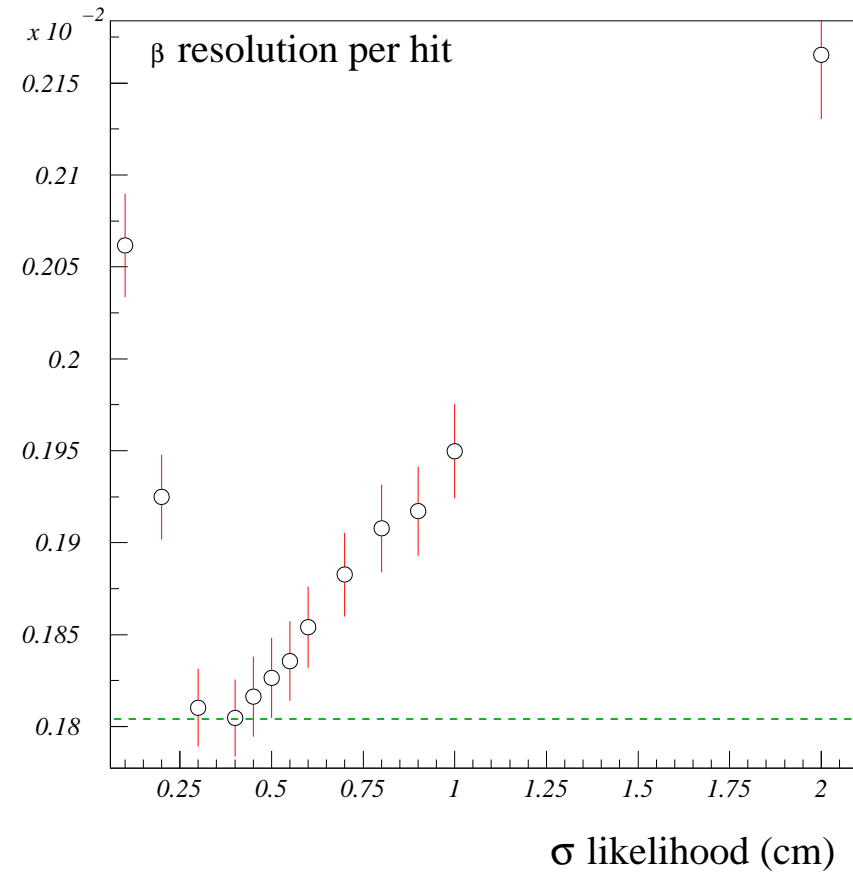
## $\theta_c$ reconstruction: effect of track resolution on $\beta$ resolution

Here there is no TRACK SMEARING !  $\beta$  resolution increases 30 %

$$\sigma = 3.2 \times 10^{-3} (\text{smearing ON}) \rightarrow 1.8 \times 10^{-3} (\text{smearing OFF})$$



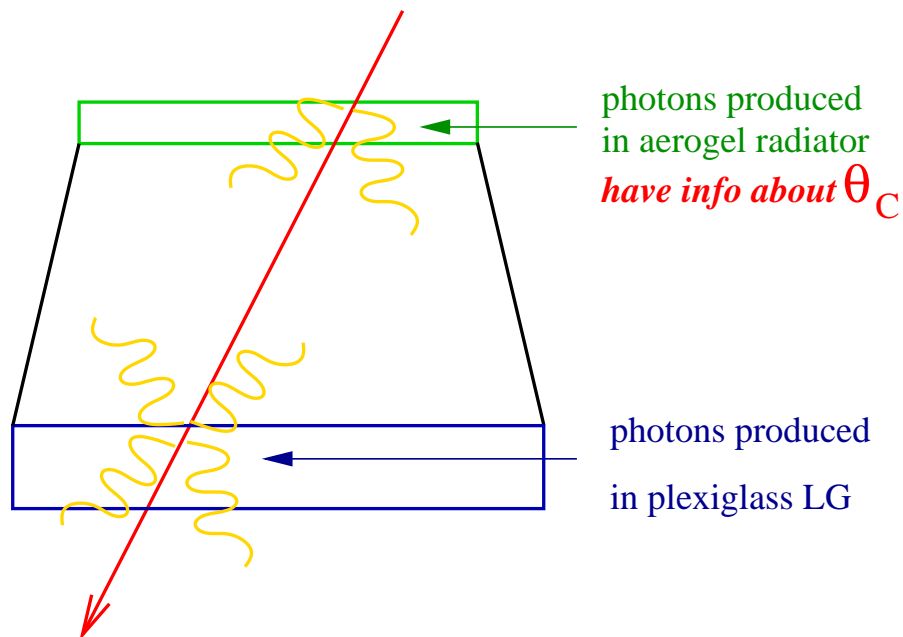
$\sigma_{\text{like}}$  set to 0.3 cm



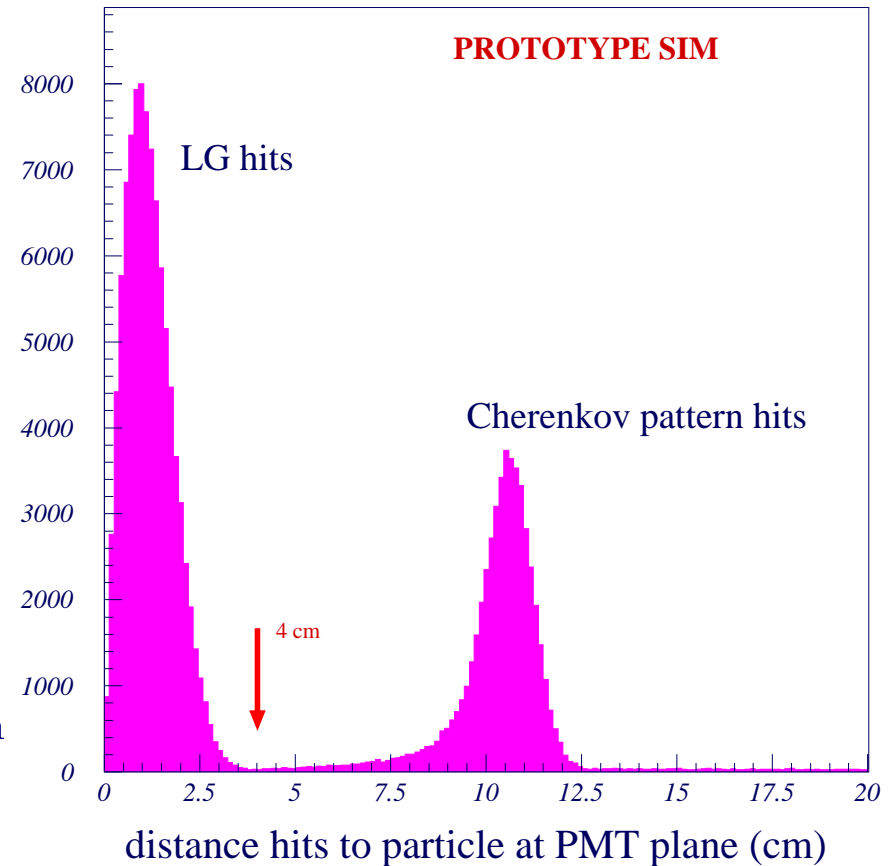
$\sigma_{\text{like}}$  set to 0.3 cm

# Particle Cluster

LG hits (hits produced by particle passage through Light Guides) are excluded from fit

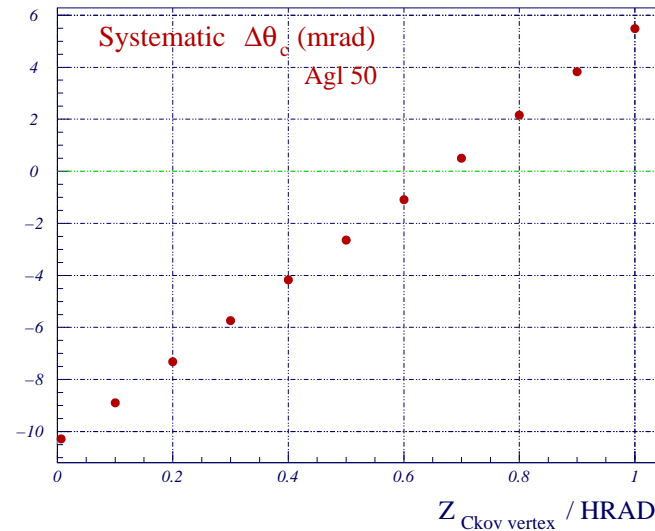
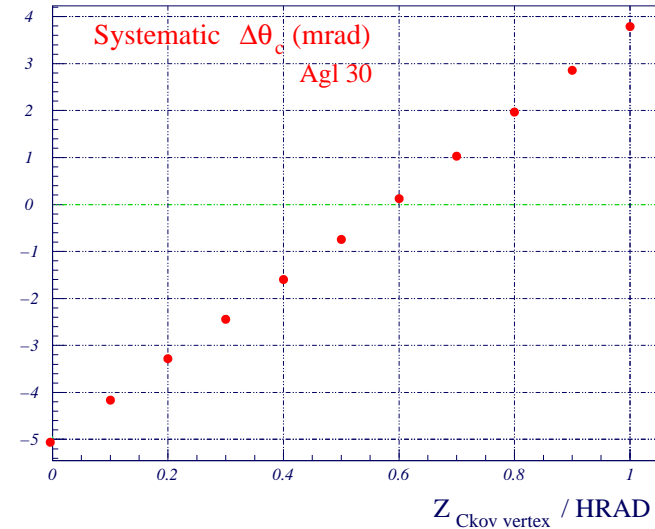
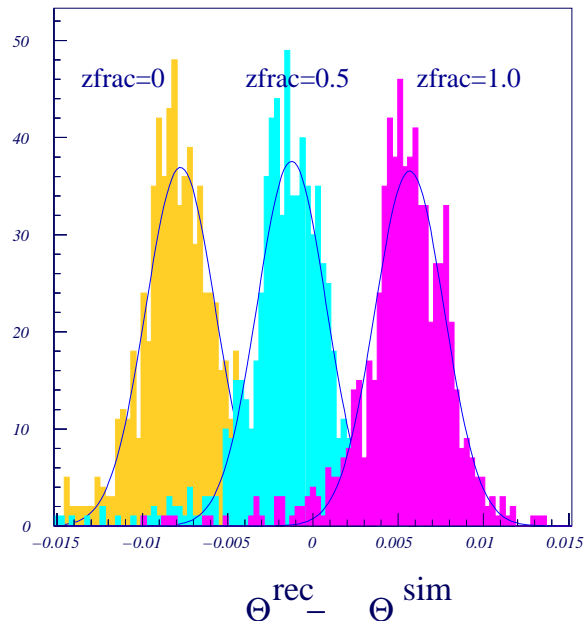
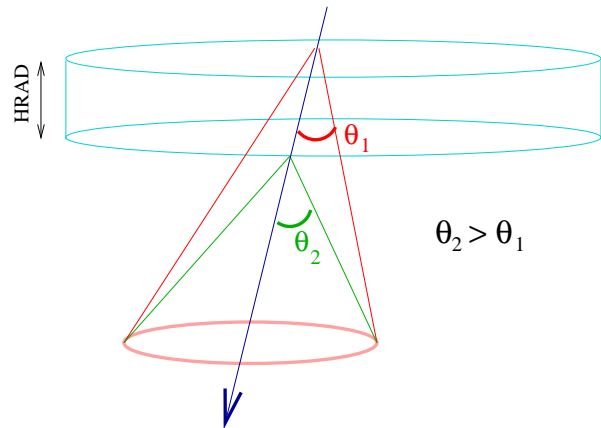


Use track extrapolation to exclude particle hits in a 4cm "window"  $\Rightarrow$

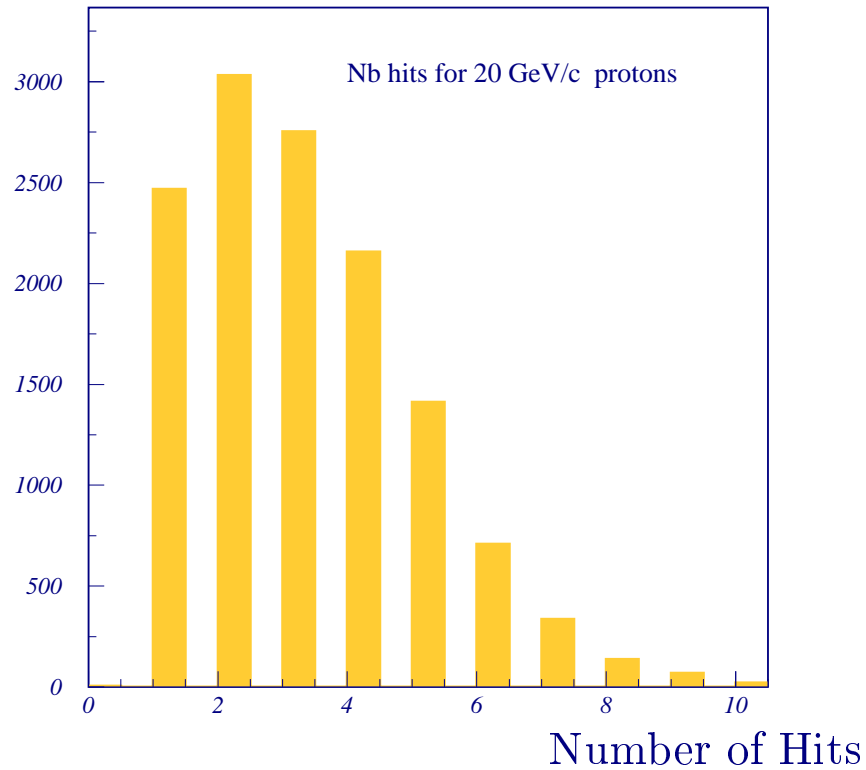




# tunning of the mean photon emission point (bias on $\theta_c^{rec}$ )

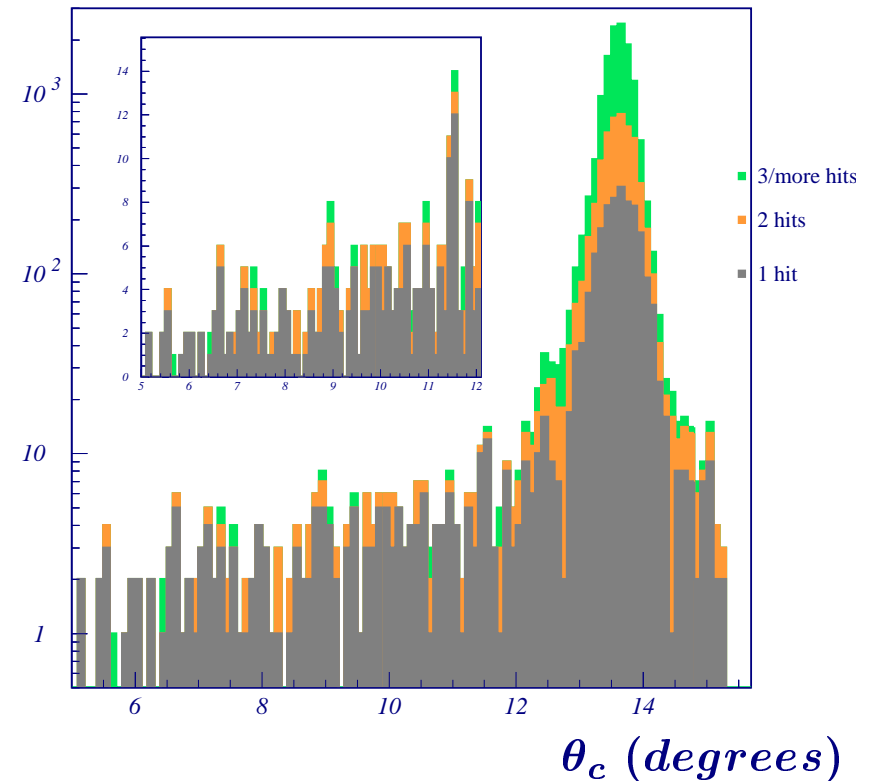


## Results: the Number of hits



radiator: aerogel ( $n=1.030$ ) 2cm thickness

☞ window for hits counting around rec pattern:  $3\sigma$



☞ large tails for events with  $\leq 3$  hits

So, keep only 3 hits reconstructions !

## Cerenkov angle resolution

→ The Cerenkov angle:

$$\cos \theta_c = \frac{1}{\beta n}$$

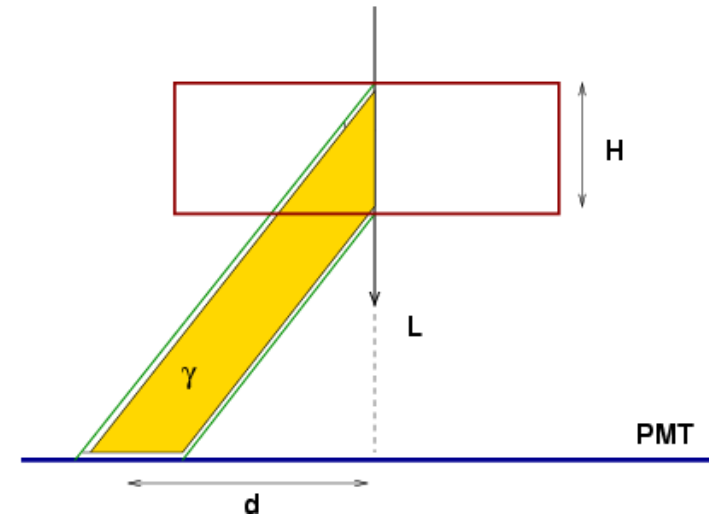
→ The particle velocity uncertainty (per hit):

$$\frac{\Delta \beta}{\beta} = \tan \theta_c \Delta \theta_c$$

→ The Cerenkov angle uncertainty:

$$\Delta \theta_c \sim \cos^2 \theta_c \frac{\Delta d}{L}$$

→ the  $\theta_c$  uncertainty deals with



❑ pixel size (granularity)  $\sim 8.5\text{mm}$

$$\Delta d \sim \frac{\text{pixel}}{\sqrt{12}}$$

$$\Rightarrow \Delta \theta_c \sim 5 \text{ mrad}$$

❑ radiator thickness  $2 - 3\text{cm}$

$$\Delta d \sim \frac{H \tan \theta_c}{\sqrt{12}}$$

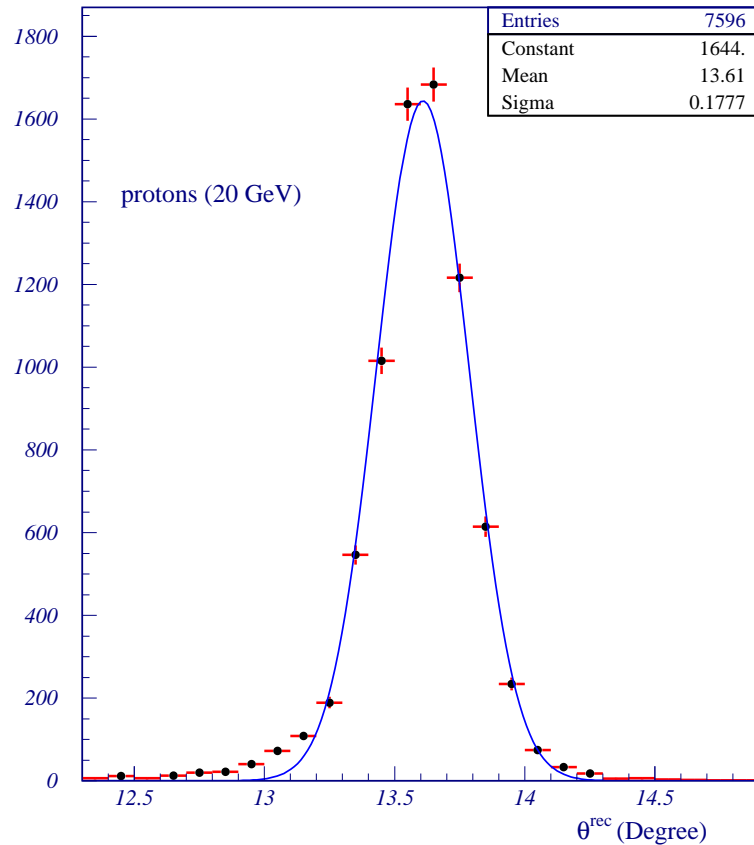
$$\Rightarrow \Delta \theta_c < 5 \text{ mrad}$$

❑ chromaticity

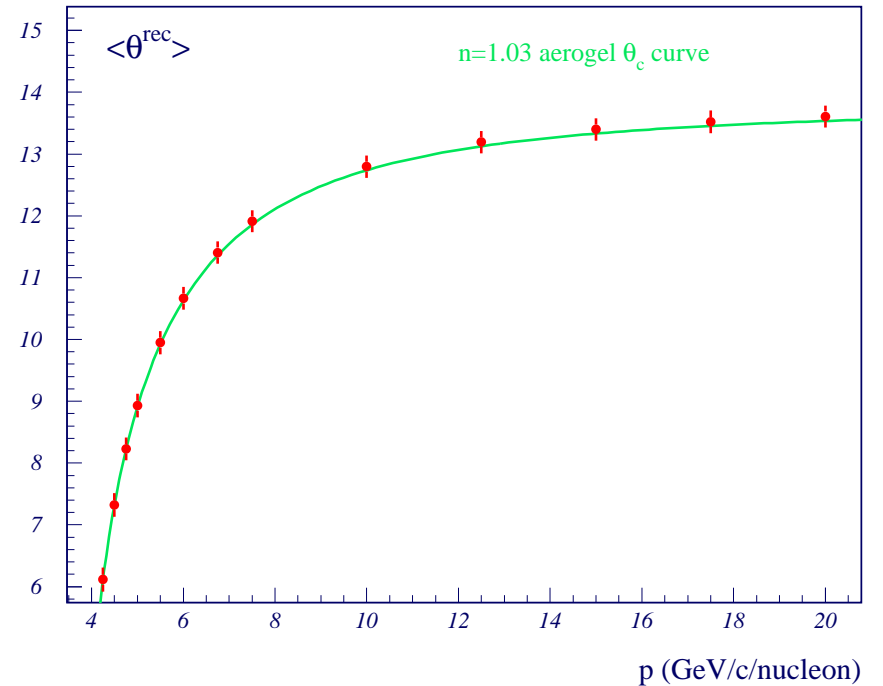
$$\Delta \theta_c \sim \frac{\Delta n}{\sqrt{2(n-1)}}$$

$$\Rightarrow \Delta \theta_c < 5 \text{ mrad}$$

# Cerenkov angle reconstruction

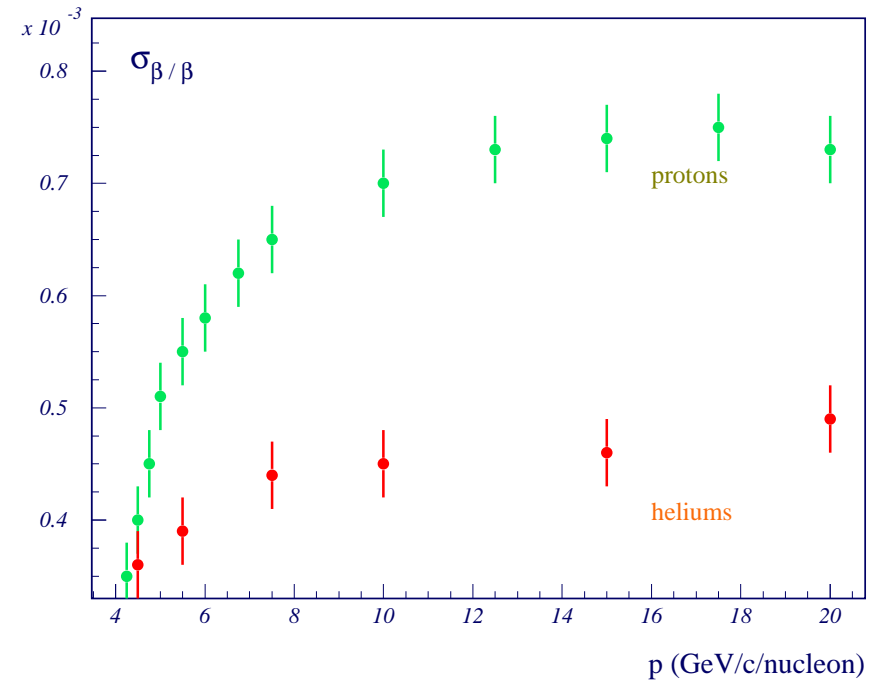
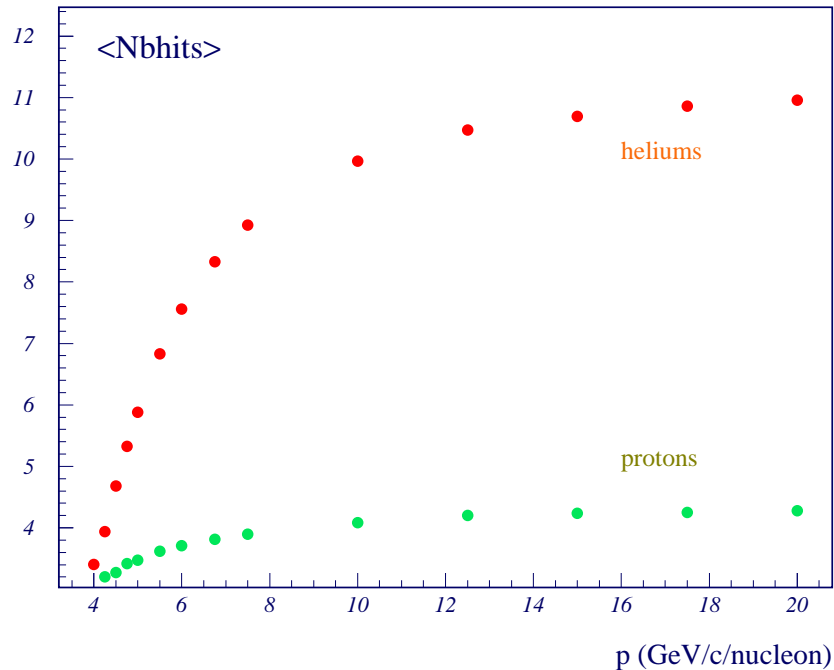


➡ Cerenkov angle reconstruction for events with at least 3 hits



➡ The reconstructed Cerenkov angle follows the expected law  $\cos\theta_c = \frac{1}{\beta n}$  at all energies

## Results : $\beta$ resolution scaling



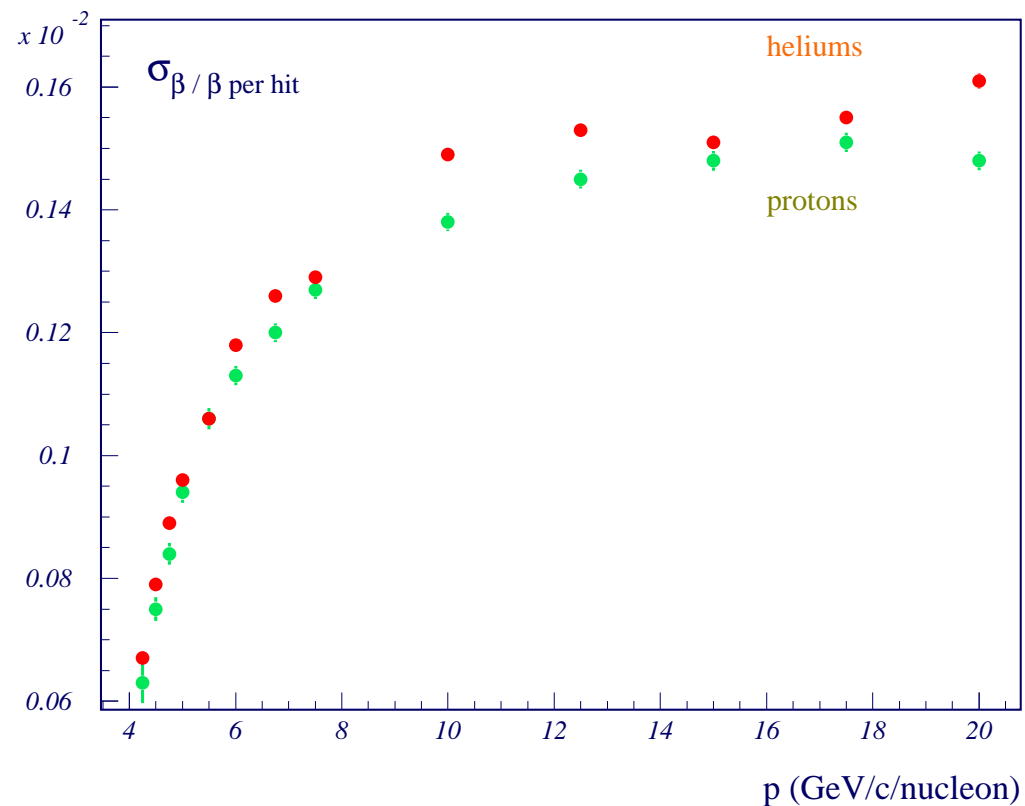
☞ the relative uncertainty on the velocity determination scales down with the number of hits

$$\frac{\Delta_{\beta}}{\beta} = \tan \theta_c \frac{\Delta_{\theta}}{\sqrt{N_{hits}}}$$

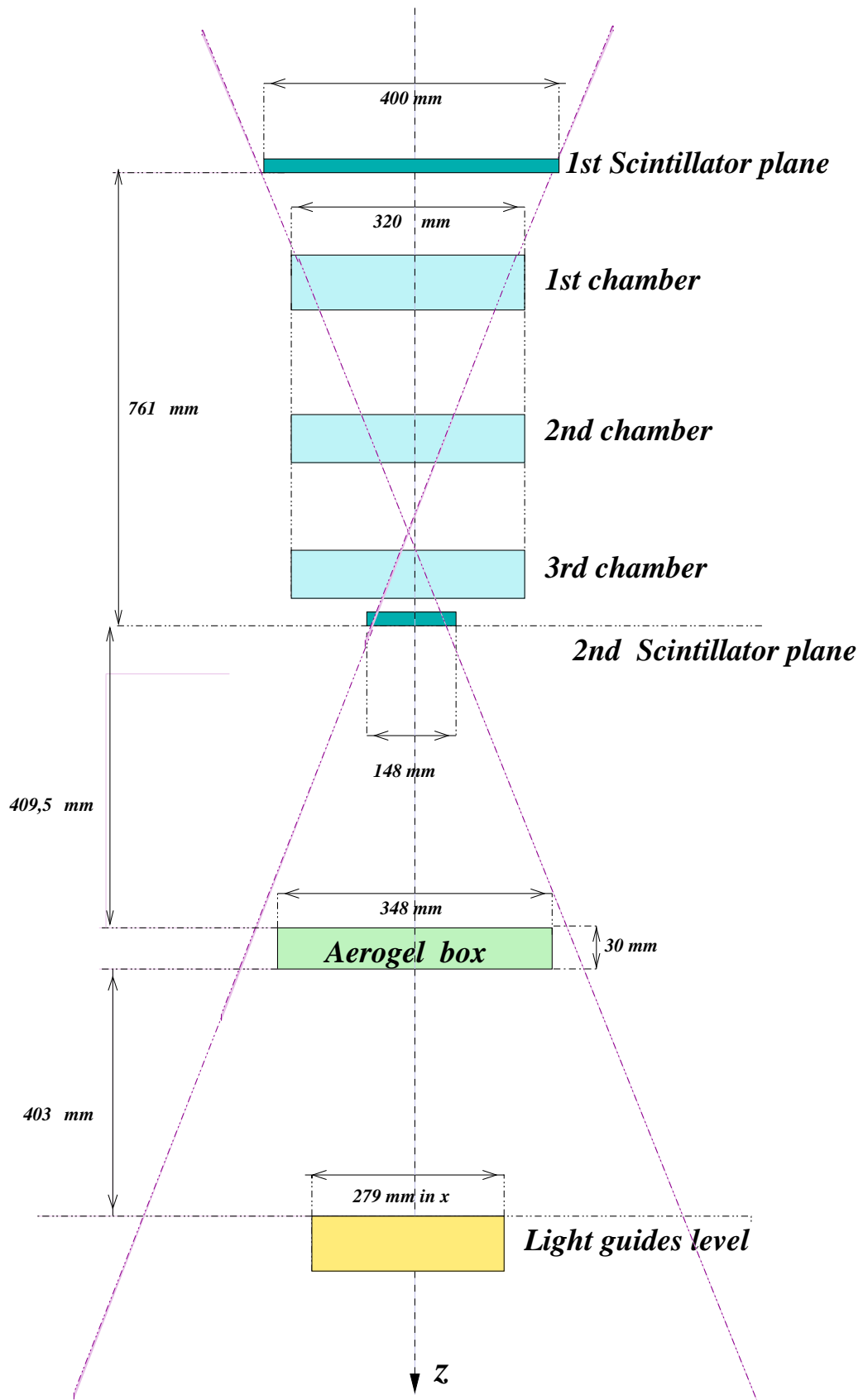
## $\Delta\beta/\beta$ : Resolution per hit

- ✓ It is possible to estimate the velocity resolution independently of the number of hits of every event

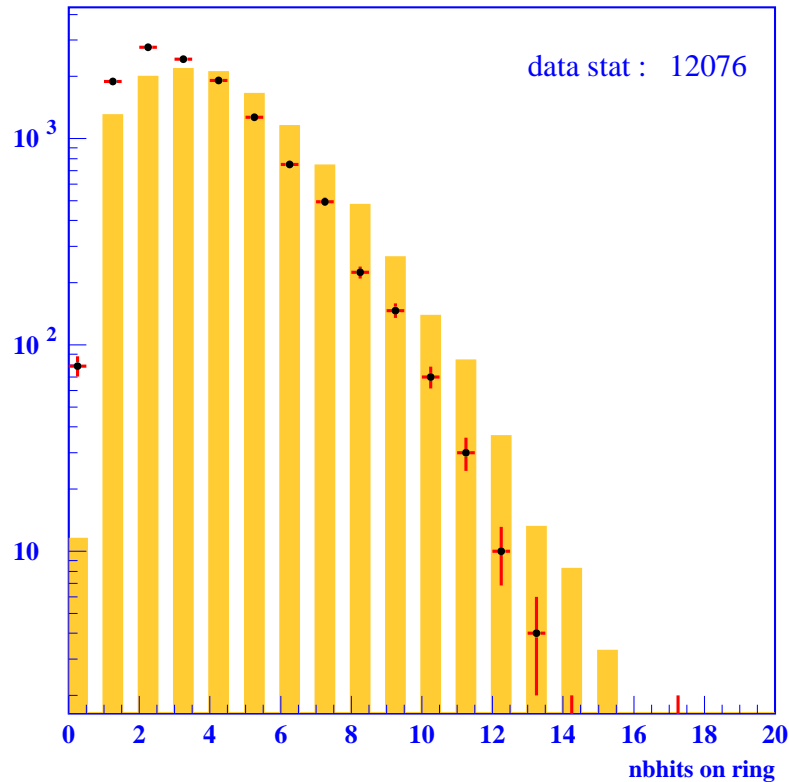
$$\left(\frac{\Delta\beta}{\beta}\right)_{hit} = \frac{\Delta\beta}{\beta} \times \sqrt{N_{hits}}$$



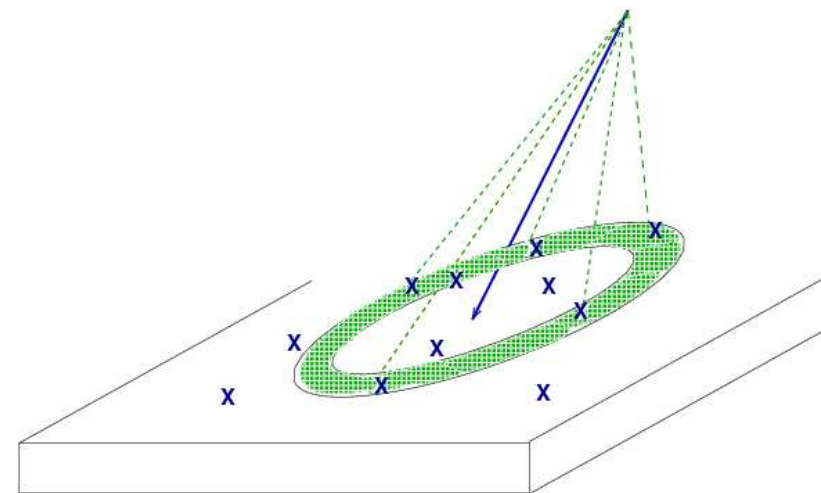
# prototype setup for RUN 21



# Prototype Data Analysis: Comparing DATA to MC



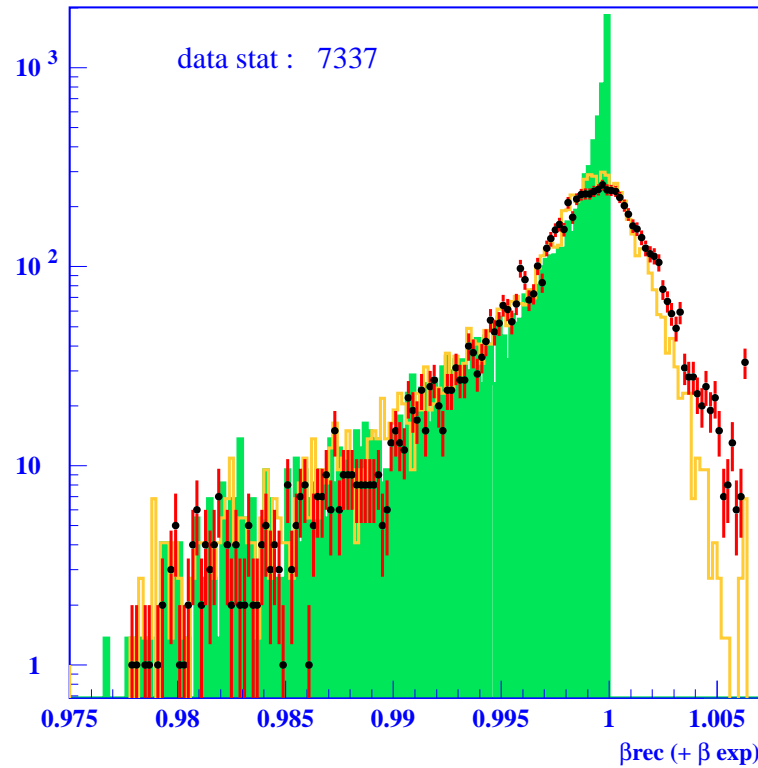
number of hits correlated with the photon pattern



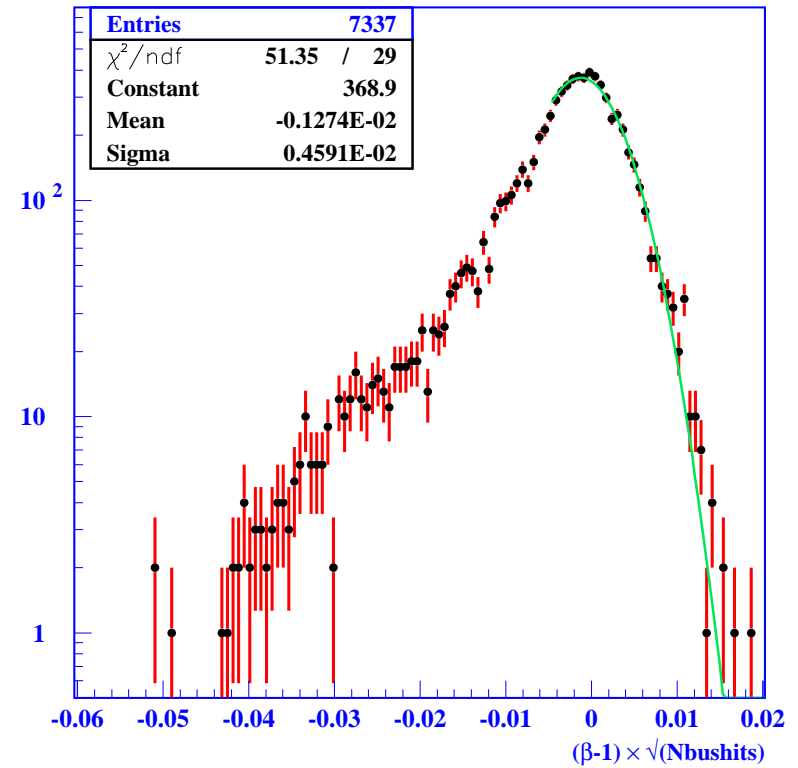
window defined by 3 sigma of rec pattern residuals distribution



# Cosmic muons velocity spectrum



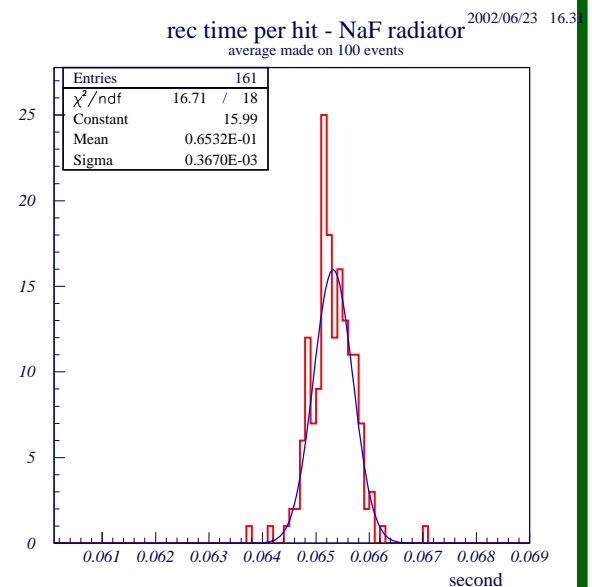
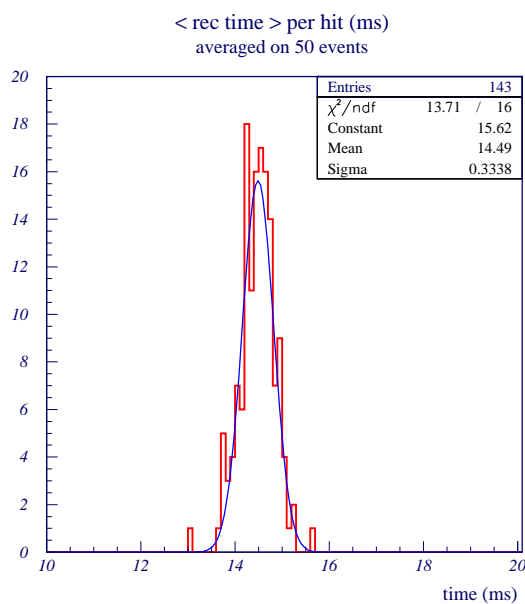
Measured  $\beta$  on data and simulation



Velocity resolution from one hit

## Conclusions and Future prospects

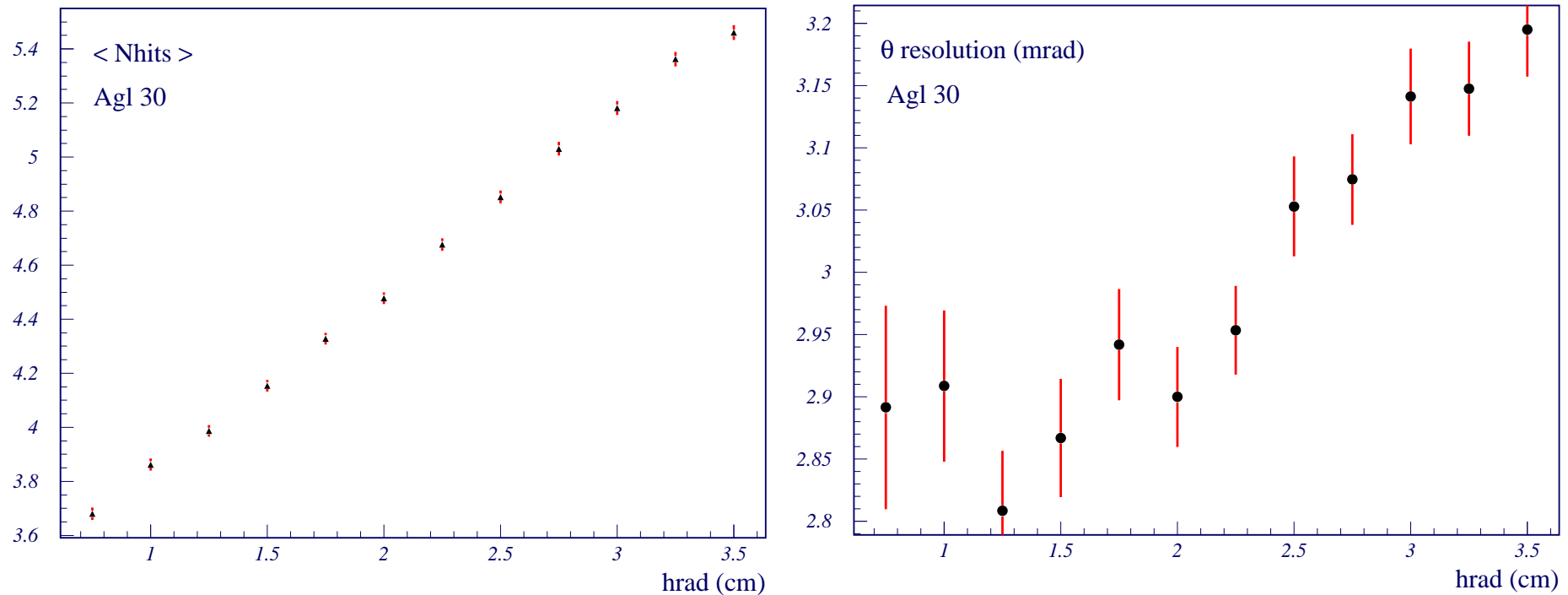
- A  $\theta_C$  reconstruction based on a likelihood fitting technique has been developed, that works fine with 2 very different radiators; Aerogel( $n=1.03$ ) and NaF( $n=1.33$ )
- Understand what is the better resolution achievable with likelihood approach
- solve some (very) few “pathological” events that give tails
- numerical improvements (in time computation) still possible



- Prototype Data (only RUN 21 for yet) has been analysed in a satisfactory way

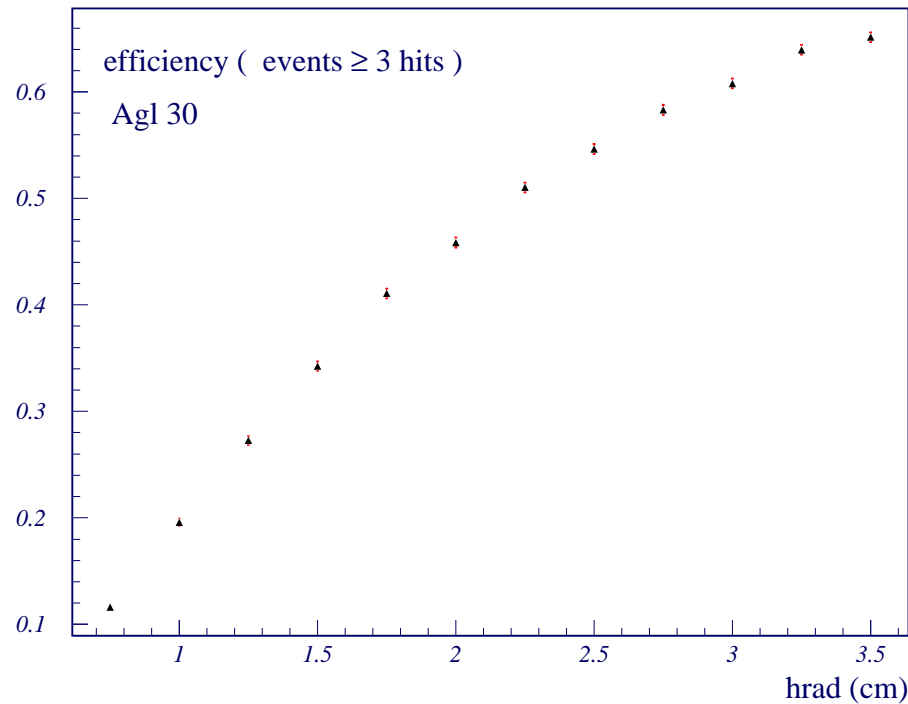
## Effect of radiator thickness

Despite increase of the pattern hits mean number, resolution has a slightly decreasing trend .



particles considered:  $Z=1$ ,  $\beta=0.999$

## Effect of radiator thickness



particles considered :  $Z=1$ ,  $\beta=0.999$

In short :

- ☞ when radiator thickness goes from 2 to 3 cm, resolution decreases  $\sim 5\%$  but reconstruction efficiency increases  $\sim 40\%$  due to increase of hits number (when referred to 2cm numbers).