

Status and plans

ESD/AOD

- More and more interest from physics groups on trigger issues (if you don't trigger on it, you can't analyse it!)
- Need to provide ways for trigger information to be available for physics analyses (i.e. in the AODs)
- This may mean several different things:
 - "Yes/No" result of hypothesis algorithms only: limited use; probably good enough for a normal physics analysis; would generate valuable feedback from physics groups
 - 2) Enough information to allow some tuning of cuts in hypothesis algorithms: more info than previous case; must include some navigation information; even more valuable feedback from physics groups; allow development of new trigger menus
 - Everything (...this means running trigger from RDOs; not feasible for physics analysis)
- Not much time left:
 - □ We should be thinking in terms of what will exist in data taking
 - □ After a first iteration we should have a close to final product
 - □ Should have first prototype in rel.11 to have time to iterate

Trigger requirements

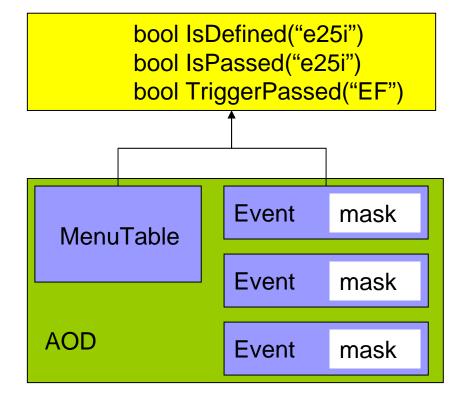
- Typical requirements on trigger data objects must include:
 - □ Speed
 - Size
 - Robustness
 - □ Maintainability
- Different uses of level 2 data classes:
 - □ Online: trigger processing; signatures...
 - Online: communication between LVL2 and EF
 - □ Offline: debugging and tuning of hypotheses
 - □ Offline: efficiency/rate studies
 - □ Offline: trigger algorithm development
- Offline uses mean storing information in Pool (ESD/AOD) and serializing information (LVL2->EF)
- It is important to maintain enough flexibility:
 - Not much information needs to be passed between LVL2 and EF in normal running, but <u>potentially every</u> LVL2 data object should be kept for a subsample of events
 - □ MC poses different constraints than online running: more information to persistify

Plans for level 2 ESD/AOD

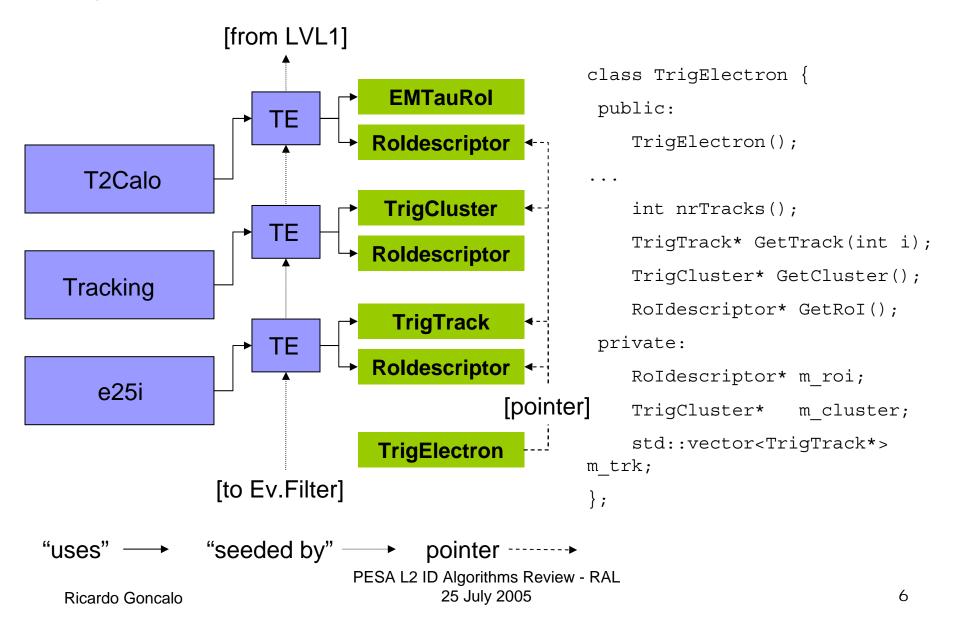
- See: http://agenda.cern.ch/fullAgenda.php?ida=a053774#2005-07-14
- Provide trigger result summaries in AOD ("Yes/No" result. More?)
 - These could be the menu table stored in the run store/conditions DB plus trigger masks stored for each event
 - Methods would be provided such as:
 - bool IsDefined("e25i")
 - bool IsPassed("e25i")
 - bool TriggerPassed("L1/L2/EF")
- Provide "slimmed-down" data classes produced by tracking/calorimetry/... algorithms
 - □ LVL1 Rol types
 - □ LVL2 tracks/clusters (redesign/slim down current ESD objects)
 - □ These would allow the possibility of re-running hypothesis algorithms
- Provide new objects as the result of hypothesis algorithms
 - TrigElectron, TrigTau, TrigMu...
 - □ These would group together tracks/clusters/Roldescriptors etc
 - □ Would be a way of storing online information
- All/some of these should be designed with data taking in mind: size, complexity, dependencies, robustness

Trigger decision

- This applies equally well to LVL1, LVL2 and EF
- Trigger decision:
 - Menu table to be stored in RunStore (may not be feasible yet)
 - Trigger masks to be stored for each event (interpreted through menu table)
 - Methods should be provided to interpret masks for each event
 - Short-term solution (for Rome data) would be to write methods that mimic this for the few signatures which were implemented
 - Long-term solution: menu table will be in conditions DB as it is part of the trigger configuration



Hypothesis result



Status of ESD/AOD trigger info

Various LVL1/LVL2 classes persistified for Rome production:

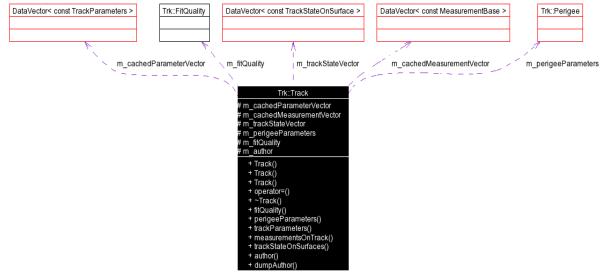
□ See: <u>http://atlas.web.cern.ch/Atlas/GROUPS/DAQTRIG/PESA/egamma/</u> rome/ESDcontents.html

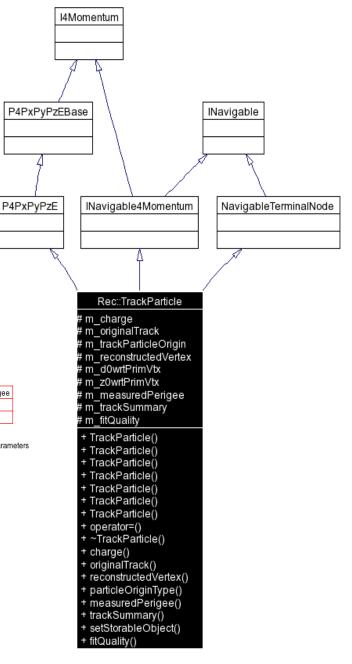
LVL1 : EMTauRol, JetRol, EtMiss

- □ LVL2 : EMShowerMinimal, TrackParticles
- TrackParticles are stored in ESD and AOD
- Persistency mechanisms already in place
- Converted from TrigInDetTrack
 - □ Using TrigT.ParticleCreator TrigToTrkTrackTool and ParticleCreatorTool
- This means creating several objects:
 - □ Trk::Track, Trk::TrackSummary
 - □ Trk::MeasuredPerigee, Trk::TrackStateOnSurface
 - □ Trk::TrackParameters, Trk::RIO_OnTrack, HepLorentzVector, etc
- This was a valid first attempt but should be revisited to find objects that are better suited to online environment
- Ideally aim to store same objects as are used in trigger
 - □ This would allow re-running of hypotheses algorithms offline

Offline

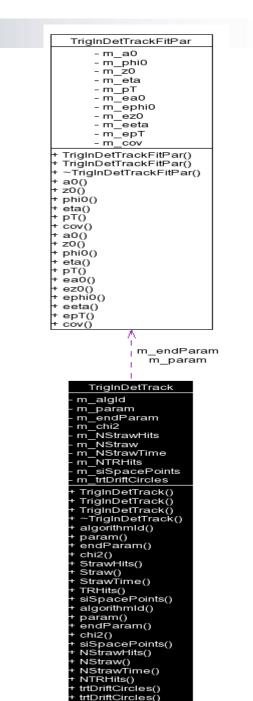
- See talk by Markus Elsing
- Offline tracking classes are flexible and can accomodate enormous complexity
- May contain only a small subset of constituent objects
- But at the cost of code complexity, large dependencies and some overheads
- E.g. a few objects pointed to by TrackParticles must be copied from constituent Trk::Tracks to maintain object ownership and avoid dangling pointers





TrigInDetTrack

- Currently produced by LVL2 tracking algorithms and used in trigger code and hypotheses algorithms
- Not great flexibility (parameters at 2 surfaces only)
- But: Simple
- No inheritance
- Few (direct) dependencies:
 - □ std::vector<>
 - TrigSiSpacePoint
 - TRT_DriftCircle
- Extrapolation to 2nd surface should be done by tracking algorithms
- Size: ~21 double + 5 int + 6 pointers + 30 double (cov. matrix) - could be even smaller if no 2nd surface
- May increase to:
 - □ + N*sizeof(TRT_DriftCircle) ->(more complicated)
 - □ + M*sizeof(SiSpacePoint) ->(~10 double +1 int)
- Should be "easy" to persistify and serialize: this would be more appropriate for LVL2 ESD/AOD



Design : constraints

- To make persistency/serialization easier <u>avoid</u>:
 - ElementLinks
 - Inheritance
- Classes should be small and simple:
 - □ Maintainable and robust (minimise dependencies)
 - □ Size must be minimal to avoid problems for online running
- Data objects would be persistified (cluster / Roldescriptor / Spacepoints?)
 - □ This assumes small numbers of objects stored for normal running but potential to store more information for debugging and efficiency studies
- "Hypothesis" classes (e.g. "TrigElectron") should have <u>pointers</u> to tracks, LAr cluster, Roldescriptor
 - □ This avoids duplication of data objects and problems from ElementLinks
 - This could be redesigned when navigation information is available and persistent/serializeable (being re-designed)
- Mainly e/gamma and tau objects currently being defined: probably equal needs for other triggers

Design : constraints

Persistency - usual recipes from:

https://uimon.cern.ch/twiki/bin/view/Atlas/WriteReadDataViaPool

- To persistify pointers:
 - □ Classes should have virtual destructor (guarantee polymorphism)
 - Default constructor should initialize all data members especially pointers
 - No pointers to STL collections (not polymorphic; must be contained by value)
 - □ Tested in simple case and works "out of the box"
- To persistify classes (the usual thing):
 - □ Classes must have dictionary fillers: lcgdict pattern
 - □ Automatic converters must be generated: poolcnv pattern
- To serialize classes (Jiri Masik, LVL2):
 - □ Classes must have dictionary fillers as for persistency
 - Classes should contain only data members of type int, float and pointers to other classes
 - Has been demonstrated; should investigate serialisation of STL containers

Conclusions and outlook

- Design should proceed with online running in mind as well as trigger signature development, debugging, etc
- It seems a good idea to minimise complexity and dependencies to improve maintainability and ease persistency/serialisation
- Classes to be serialised need to be simple
- Ideally store same classes that are used in trigger hypotheses
- What could be stored in POOL for algorithm development?
 - This is very important and would mean faster development and improved algorithms
 - □ But it must be balanced against how much we can store
 - □ ESD? New, lighter data structure just for this?
- Prototype "hypothesis" classes could be done soon
- Same subjects also under discussion in muon community : common solutions should be explored whenever possible
- New ESD/AOD classes should be available and validated in release 11 to allow time for redesign